

Errata in thesis\_ Phd. Aerospace Engineering, Aug. 2012, Seung Pil Kim

p. 11 (line19) 1000 -> 1,000

p. 12 (line 3)  $\Delta v$ ->  $\Delta V$

p. 12 (line 5) As the the -> As the

p. 20 (line 7) Equsion -> Equation

p. 24 (end line) cite [?] -> Betts

p. 40 (line 6) psduedospectral -> pseudospectral

p. 48(in Eq. 3.20)  $L_n$  -> $L_N$

P.48 (the last line)

the pseudospectral domain performance index can be replaced  
-> the pseudospectral domain can be replaced

p.49 (line 7) a simple to solve nonlinear program -> a simple nonlinear program

p. 78(line 2 from the last)  $K = 0.01$  ->  $acc=0.01$

p. 79(line 4) Table (4.2)-> Table (4.3)

p. 80(line 3) It and then -> It

p. 88( in Figure 4.11) Caption change : Trajectories -> Control

p. 96(in Figure 4.21) Figure change : Tangential Velocity -> Control

p. 105(line 7) Eq.(A.12) -> Eq(A. 10)

p.143(line 8-9) Journal of Guidance, Contro,l and -> Guidance, Control, and