
p. 11 (line19) 1000 -> 1,000
p. 12 (line 3) Δν-> ΔV
p. 12 (line 5) As the the -> As the
p. 20 (line 7) Equstion -> Equation
p. 24 (end line) cite [?] -> Betts
p. 40 (line 6) psduedospectral -> pseudospectral
p. 48(in Eq. 3.20) L_n -> L_N
P48 (the last line) the pseudospectral domain performance index can be replaced
-> the pseudospectral domain can be replaced
p.49 (line 7) a simple to solve nonlinear program -> a simple nonlinear program
p. 78(line 2 from the last) K = 0.01 -> acc=0.01
p. 79(line 4) Table (4.2)-> Table (4.3)
p. 80(line 3) It and then -> It
p. 88( in Figure 4.11) Caption change : Trajectories -> Control
p. 96(in Figure 4.21) Figure change : Tangential Velocity -> Control
p. 105(line 7) Eq.(A.12) -> Eq(A. 10)
p.143(line 8-9) Journal of Guidance, Control, and -> Guidance, Control, and